

# CLOCK RECOVERY CIRCUIT CAPABLE OF AUTOMATICALLY ADJUSTING FREQUENCY RANGE OF VCO

## BACKGROUND OF THE INVENTION

### Field of the Invention

5           The invention relates to clock recovery circuit, and more particularly to a clock recovery circuit capable of automatically adjusting the frequency range of a VCO (Voltage Controlled Oscillator) in the circuit without needing a look-up-table.

### Description of the Related Art

10           Typically, an optical disk drive operates an optical disk at a constant angular velocity, so the linear speeds at the inner tracks and outer tracks of the optical disk are different. In this case, the frequencies of a reference clock to read the EFM (Eight-To-Fourteen Modulation) signal at different tracks for the optical disk drive are also different. In order to correctly read the information on different tracks of the optical disk, the optical disk drive must utilize a clock recovery circuit (or a phase  
15   locked loop) to generate a reference clock in synchronization with the EFM signal.

          FIG. 1 shows a typical EFM clock recovery circuit. The clock recovery circuit 100 includes a phase detector 101, a frequency detector 102, a charge pump 103 for receiving the output signal PDO of the phase detector 101 and the output signal FDO of the frequency detector 102, a loop filter 104 connected to the charge pump 103, a  
20   voltage controlled oscillator (hereinafter referred as VCO) 105 for receiving a fine control voltage VT outputted from the loop filter 104, and a frequency divider 106 for generating the reference clock FCO by dividing the frequency of the oscillation clock outputted from the VCO 105. In the clock recovery circuit 100, the functions of the

phase detector 101, the frequency detector 102, the charge pump 103, the loop filter 104, the VCO 105 and the frequency divider 106 are the same as those of the typical phase locked loop, and detailed descriptions thereof will be omitted. In addition to the above-mentioned components, the clock recovery circuit 100 further includes a counter 5 107 for generating a frequency value of the reference clock FCO, a control unit 108, and a DAC (Digital to Analog Converter) 109. The counter 107 counts the frequency of the reference clock FCO outputted from the frequency divider 106, and generates the frequency value FV to the control unit 108. The control unit 108 chooses a control value from a look-up-table according to the frequency value FV. The DAC 109 10 converts the control value into an analog coarse control voltage RVT to control the frequency range of the VCO 105.

In this clock recovery circuit 100, however, the control unit 108 thereof has to create a look-up-table, as shown in FIG. 2. That is, the relationship between the central frequency of the frequency range of the VCO (i.e.,  $F_{Ri}$ ,  $i=1\sim9$ ) and the coarse control 15 voltage RVT has to be determined in advance. Based on the preset look-up-table, a central frequency closest to the reference clock FCO is picked, and the corresponding coarse control voltage in the table is fed to the DAC 109 so as to set the coarse control voltage RVT to adjust the frequency range of the VCO 105.

### SUMMARY OF THE INVENTION

20 It is therefore an object of the invention to provide a clock recovery circuit capable of automatically adjusting frequency range of a VCO without involving a look-up-table.

To achieve the above-mentioned objects, the clock recovery circuit of the present

invention includes a phase detector, a main frequency detector, a main loop filter, a main VCO, an auxiliary frequency detector, an auxiliary loop filter, and an auxiliary VCO. The phase detector receives an input signal and a main oscillation clock and generates a phase error signal. The main frequency detector receives the input signal and the main oscillation clock and generates a frequency error signal. The main loop filter receives the phase error signal and the frequency error signal and generates a fine control voltage. The main VCO receives the fine control voltage and a coarse control voltage and generates the main oscillation clock. The auxiliary frequency detector receives the main oscillation clock and an auxiliary oscillation clock and generates an auxiliary frequency error signal. The auxiliary loop filter receives the auxiliary frequency error signal and generates the coarse control voltage. The auxiliary VCO receives the coarse control voltage and a reference fine control voltage and generates the auxiliary oscillation clock.

By using an auxiliary loop in the present invention, the adjustment of the coarse control voltage of the main loop is automatically performed by the auxiliary loop, and need not to involve a look-up-table .

### **BRIEF DESCRIPTION OF THE DRAWINGS**

FIG. 1 illustrates a typical EFM clock recovery circuit.

FIG. 2 illustrates a look-up-table for the clock recovery circuit of FIG. 1.

FIG. 3A illustrates a block diagram of a clock recovery circuit of the invention.

FIG. 3B illustrates another block diagram of a clock recovery circuit of the invention.

FIG. 4 illustrates the relation curve of the fine control voltage  $V_T$  and the coarse

control voltage RVT versus the frequency of the input signal EFM.

### DETAILED DESCRIPTION OF THE INVENTION

The clock recovery circuit of the invention will be described with reference to the accompanying drawings.

5        FIG. 3A illustrates a block diagram of a clock recovery circuit of the invention, which is capable of automatically adjusting the frequency range of a VCO. Referring to FIG. 3A, the clock recovery circuit 30 includes a main loop 31 and an auxiliary loop 32. The main loop 31 includes a phase detector 311, a main frequency detector 312, a main loop filter 313 connected to the phase detector 311 and the main frequency  
10    detector 312, a main VCO 314 for receiving a fine control voltage VT of the main loop filter 313, and a frequency divider 315. The main loop 31 is a typical phase locked loop (PLL), so the function and architecture of each unit will not be described again. Note that the frequency divider 315 also may be omitted, as shown in Fig. 3B.

The auxiliary loop 32 includes an auxiliary frequency detector 322, an auxiliary  
15    loop filter 323, and an auxiliary VCO 324. The auxiliary frequency detector 322 receives a main oscillation clock FCO1 generated by the main VCO 314 and an auxiliary oscillation clock FCO2 generated by the auxiliary VCO 325, and then outputs a frequency error value VE. The auxiliary loop filter 323 receives the frequency error value VE, filters the frequency error value VE, and then generates a coarse control  
20    voltage RVT. Finally, the auxiliary VCO 324 sets the frequency range according to the coarse control voltage RVT, and generates the auxiliary oscillation clock FCO2 according to a reference fine control voltage VR. The main VCO 314 utilizes the coarse control voltage RVT to set its frequency range, and utilizes the fine control

voltage  $V_T$  outputted from the main loop filter 313 to adjust the frequency of the main oscillation clock FCO1.

In general, the frequency  $f_{FCO}$  of the oscillation clock of a VCO is known to be:

$$f_{FCO} = k_1 * V_1 + k_2 * V_2 \dots(1),$$

5 wherein  $k_1$  and  $k_2$  are design parameters of the VCO,  $k_2$  is larger than  $k_1$ ,  $V_2$  is the coarse control voltage for adjusting the frequency range of the oscillation clock of a VCO, and  $V_1$  is the fine control voltage for controlling the frequency of the oscillation clock of a VCO. Therefore, if the design parameters of the main VCO 314 and the auxiliary VCO 324 are the same, the frequencies of the main oscillation clock FCO1 of  
10 the main VCO 314 and the auxiliary oscillation clock FCO2 of the auxiliary VCO 324 are:

$$f_{FCO1} = k_1 * V_T + k_2 * RVT \dots(2), \text{ and}$$

$$f_{FCO2} = k_1 * V_R + k_2 * RVT \dots(3).$$

where  $f_{FCO1}$  and  $f_{FCO2}$  denotes the frequencies of the main oscillation clock FCO1 and  
15 that of the auxiliary oscillation clock FCO2, respectively.

As mentioned, the coarse control voltage RVT is generated by the auxiliary loop 32. So, when the main oscillation clock FCO1 and the auxiliary oscillation clock FCO2 have different frequencies, the coarse control voltage RVT will be changed therewith. The control principle of the invention will be described in the following.

20 First, once in the steady state, the main oscillation clock FCO1 will synchronize to the input signal EFM, and the auxiliary oscillation clock FCO2 will synchronize to the main oscillation clock FCO1. In other words, the frequency of the main oscillation clock FCO1 will equal to that of the input signal EFM, and the frequency of the

auxiliary oscillation clock FCO2 will equal to that of the main oscillation clock FCO1.

When the frequency of the input signal EFM increases, the fine control voltage VT will increase correspondingly, so that the frequency of the main oscillation clock FCO1 can be in synchronization with the frequency of the input signal EFM. At the  
5 meantime, because the frequency of the main oscillation clock FCO1 becomes higher than that of the auxiliary oscillation clock FCO2, the coarse control voltage RVT will be risen correspondingly. In the condition when the coarse control voltage RVT is risen, the frequency of the main oscillation clock FCO1 is forced to be higher than that of the input signal EFM, and the fine control voltage VT is reduced so as to prevent the  
10 too-high fine control voltage VT from saturating the main VCO 314. On the other hand, the frequency of the auxiliary oscillation clock FCO2 also rises to follow the frequency of the main oscillation clock FCO1. Therefore, when the system reaches the steady state, the main oscillation clock FCO1 will be eventually in synchronization with the input signal EFM again, and the frequency of the auxiliary oscillation clock FCO2  
15 will be equal to that of the main oscillation clock FCO1. Meanwhile, the fine control voltage VT will be equal to the reference fine control voltage VR. Consequently, the fine control voltage VT is controlled at a proper position without the risk of causing the saturation of the main VCO 314 as long as the reference fine control voltage VR is properly set. Furthermore, a good linear operation range of the main VCO 314 is  
20 provided.

Next, when the frequency of the input signal EFM is reduced, the fine control voltage VT will be reduced correspondingly such that the frequency of the main oscillation clock FCO1 can be in synchronization with the frequency of the input signal

EFM. At this time, because the frequency of the main oscillation clock FCO1 becomes lower than that of the auxiliary oscillation clock FCO2, the coarse control voltage RVT is also reduced therewith. In the condition when the coarse control voltage RVT is reduced, the frequency of the main oscillation clock FCO1 is forced to  
5 be lower than that of the input signal EFM, and the fine control voltage VT is risen so as to prevent the too-low fine control voltage VT from saturating the main VCO 314. On the other hand, the frequency of the auxiliary oscillation clock FCO2 also reduces to follow the frequency of the main oscillation clock FCO1. Therefore, when the system reaches the steady state, the main oscillation clock FCO1 will be eventually in  
10 synchronization with the input signal EFM, and the frequency of the auxiliary oscillation clock FCO2 will be equal to that of the main oscillation clock FCO1. Meanwhile, the fine control voltage VT will be equal to the reference fine control voltage VR. Consequently, the fine control voltage VT is controlled at a proper position without risk of causing the saturation of the main VCO 314 as long as the  
15 reference fine control voltage VR is properly set. Furthermore, a good linear operation range of the main VCO 314 is provided.

FIG. 4 illustrates the relation curve of the fine control voltage VT and the coarse control voltage RVT versus the frequency of the input signal EFM, according to the present invention. As shown in FIG. 4, when the frequency of the EFM signal changes  
20 from low to high, the coarse control voltage RVT also increases therewith such that the fine control voltage VT of the main VCO 314 is held at a preset constant value VR. Consequently, the fine control voltage VT of the main VCO 314 will never be saturated and the main VCO 314 will operate in the linear zone as long as the reference fine

control voltage VR is selected to be a proper voltage value.

Hence, the clock recovery circuit of the invention utilizes an auxiliary loop to automatically adjust the coarse control voltage of the VCO of the main loop. So, it is possible to effectively prevent the VCO from reaching the saturation state without  
5 preparing a look-up-table previously.

While certain exemplary embodiments have been described and shown in the accompanying drawings, it is to be understood that such embodiments are merely illustrative of and not restrictive on the broad invention, and that this invention not be limited to the specific construction and arrangement shown and described, since various  
10 other modifications may occur to those ordinarily skilled in the art.